Solving fully coupled FBSDEs by minimizing a directly calculable error functional



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Fully coupled FBSDEs

$$X_t = X_0 + \int_0^t \mu(s, X_s, Y_s, Z_s) ds + \int_0^t \sigma(s, X_s, Y_s, Z_s) dW_s,$$

$$Y_t = \xi(X_T) - \int_t^T f(s, X_s, Y_s, Z_s) ds - \int_t^T Z_s dW_s.$$

Vision: How to check solvability numerically?

Before: Some known facts on existence and uniqueness

Existence on a small interval

Known fact:

- Under a standard Lipschitz condition (SLC) on $\mu,\,\sigma,\,f$ and ξ
- and if $L_{\xi} < L_{\sigma,z}^{-1}$,

then there exists an interval [t, T] on which a solution of the FBSDE exists.

Idea of the proof: Picard interations

Useful: decoupling fields

A function $u: \Omega \times [t, T] \times \mathbb{R} \to \mathbb{R}$ with $u(T, \cdot) = \xi$ is a *decoupling field* if for all $[t_1, t_2] \subset [t, T]$ and $x \in \mathbb{R}$ there exist progr. mb. processes (X, Y, Z) such that

$$X_{s} = x + \int_{t_{1}}^{s} \mu(r, X_{r}, Y_{r}, Z_{r}) dr + \int_{t_{1}}^{s} \sigma(r, X_{r}, Y_{r}, Z_{r}) dW_{r},$$

$$Y_{s} = Y_{t_{2}} - \int_{t}^{t_{2}} f(r, X_{r}, Y_{r}, Z_{r}) dr - \int_{s}^{t_{2}} Z_{r} dW_{r}.$$

and

$$u(s, X_s) = Y_s, \qquad s \in [t_1, t_2].$$

- u is the same, regardless of $[t_1, t_2]$
- u is an additional structure

Theoretical background

Theorem

Under (SLC) and if $L_{\xi} < L_{\sigma,z}^{-1}$, then there exists t < T such that on [t, T]

- the FBSDE has a unique solution
- ▶ th. ex. a decoupling field u
- u is Lipschitz continuous
- $\sup_{s \in [t,T]} L_{u(s,\cdot)} < L_{\sigma,z}^{-1}$

Characterizing the maximal existence interval with the decoupling field

By pasting existence intervals together one can show

$$I_{\max} = [0, T]$$
 or $I_{\max} = (t_{\min}, T]$

Theorem If $I_{max} \neq [0, T]$, then

$$\lim_{t \downarrow t_{\min}} L_{u(t,\cdot)} = L_{\sigma,z}^{-1} \tag{1}$$

(1) is very useful: If no explosion, then $I_{max} = [0, T]$.

Method of Decoupling fields (as described by Alexander Fromm)

Prove global solvability via the following steps:

- 1. Consider arbitrary [t, T] on which u exists. Let $x \in \mathbb{R}^n$ be the initial condition.
- 2. Differentiate the FBSDE wrt x to obtain the dynamics of $\frac{d}{dx}X, \frac{d}{dx}Y, \frac{d}{dx}Z$.
- 3. Use the ltô formula to obtain dynamics of $\Psi_s := u_x(s, X_s) = \frac{d}{dx} Y_s \left(\frac{d}{dx} X_s\right)^{-1}$.
- 4. Show that $\|\Psi\|_{\infty}$ is bounded away from $L_{\sigma,z}^{-1}$ independently of t < T.

Then the equation must be solvable on [0, T].

A measure for how well two Ito processes solve an FBSDE

Ito processes

Let X and Y be two Ito processes on $I = [a, b] \subset [0, T]$.

Notation:

$$X_{s} = X_{a} + \int_{a}^{s} DX_{r}dr + \int_{a}^{s} \mathfrak{D}X_{r}dW_{r},$$
$$Y_{s} = Y_{a} + \int_{a}^{s} DY_{r}dr + \int_{a}^{s} \mathfrak{D}Y_{r}dW_{r},$$

 $s \in [a, b].$

An error functional for a pair of Ito processes

For 2 Ito processes X and Y we define

$$\begin{split} & \mathcal{G}_{x,I,\zeta}(X,Y) := \\ & \mathbb{E}\bigg[|X_a - x|^2 + |I| \cdot \int_a^b |DX_r - \mu(r,\Theta_r)|^2 \,\mathrm{d}r + \int_a^b |\mathfrak{D}X_r - \sigma(r,\Theta_r)|^2 \,\mathrm{d}r \\ & + |I| \cdot \int_a^b |DY_r - f(r,\Theta_r)|^2 \,\mathrm{d}r + |Y_b - \zeta(X_b)|^2\bigg], \end{split}$$

where

- |I| = the length of the interval I
- x is the initial condition for the forward equation
- ζ defines the terminal condition of the backward equation

$$\bullet \ \Theta_r = (X_r, Y_r, \mathfrak{D}Y_r)$$

Properties of the error functional

- If G_{x,I,ζ}(X, Y) = 0, then (X, Y, DY) solve the FBSDE on I with initial condition X_a = x and terminal condition Y_b = ζ(X_b).
- Evaluation of G does not require the knowledge of (X*, Y*), the minimizer.

Properties of the error functional cont'd

Informal theorem There exists a nice norm $\|\cdot\|_1$ on the set of Ito processes and constants c < C such that for all X, Y

$$c\|(X,Y)-(X^*,Y^*)\|_1 \leq \sqrt{G(X,Y)} \leq C\|(X,Y)-(X^*,Y^*)\|_1$$

Minimizing G is in a sense equivalent to solving the FBSDE

Stochastic polynomials

Definition of stochastic polynomials

$$L^2(I):=\{X:\Omega imes I o \mathbb{R} ext{ progr. mb. with } E\int_a^b X_s^2 ds <\infty\}.$$

P(I) is defined as the smallest subset of L²(I) satisfying
P(I) is an R - vector space, which contains all constants;
if X ∈ P(I), then s ↦ ∫_a^s X_rr is also in P(I);
if X ∈ P(I), then s ↦ ∫_a^s X_rdW_r is also in P(I).

Example

$$\alpha_1 + \alpha_2(s-a) + \alpha_3(W_s - W_a) + \alpha_4 \int_a^s (W_r - W_a) \, \mathrm{d}W_r, \quad (2)$$

Let $\mathcal{P}^{3/2}$ be the set of Ito processes of the form (2).

Outlook. $\mathcal{P}^{3/2}$ is the minimal set of polynomials for approximating (general) FBSDEs

Why is $\frac{3}{2}$ minimal?

To explain this, let for $\alpha, \beta \in \mathbb{R}^4$

$$X^{lpha} := lpha_1 + lpha_2(s-a) + lpha_3(W_s - W_a) + lpha_4 \int_a^s (W_r - W_a) dx W_r,$$

 $Y^{eta} := eta_1 + eta_2(s-a) + eta_3(W_s - W_a) + eta_4 \int_a^s (W_r - W_a) dx W_r,$

Aim: finding a good $\mathcal{P}^{3/2} \times \mathcal{P}^{3/2}$ approximation of the FBSDE components X, Y. To this end minimize

$$G_{\mathsf{x},\mathsf{I},\zeta}(lpha,eta) := G_{\mathsf{x},\mathsf{I},\zeta}(X^{lpha},Y^{eta})$$

over all $\alpha, \beta \in \mathbb{R}^4$.

Why is $\frac{3}{2}$ minimal?

Theorem

For the minimizers α^*, β^* we have

$$\sqrt{G_{x,I,\zeta}}(\alpha^*,\beta^*) \in \mathcal{O}(|I|^{\frac{3}{2}})$$

Total error

$$\sqrt{G_{x,I,\zeta}}(\alpha^*,\beta^*) \in \mathcal{O}(|I|^{\frac{3}{2}})$$

- Split [0, T] into N subintervals of length $\frac{T}{N}$.
- At time t_j = ^j/_N T choose ζ = ũ(t_{j+1}, ·), the approximation of the dec. field at t_{j+1}
- Error on each subinterval: $\in \mathcal{O}((\frac{1}{N})^{\frac{3}{2}})$
- If the error propagation can be controlled, then the total error is of the order

$$\mathsf{N}\;(\frac{1}{N})^{\frac{3}{2}} = \sqrt{\frac{1}{N}}$$

Idea for an algorithm

- 1. Select a time discretization $0 = t_0 < t_1 < \cdots < t_N = T$.
- **2**. Select a set of supporting points $\{x_1, x_2, \ldots, x_S\} \subset \mathbb{R}$.
- **3.** Set j = N 1.
- 4. For every supporting point x_k find the parameters $\alpha_1^*, \ldots, \alpha_4^*$ and $\beta_1^*, \ldots, \beta_4^*$ that minimize $(\alpha, \beta) \mapsto G(X^{\alpha}, Y^{\beta})$. Set $w(t_j, x_k) = \beta_1^*$.
- 5. Choose a smooth function $\tilde{u}(t_j, \cdot)$ such that $\tilde{u}(t_j, x_k)$ is close to $w(t_j, x_k)$ for all $k \in \{1, \ldots, S\}$.
- **6.** If $j \neq 0$, then set j = j 1 and go to 4.

Literature

- Stefan Ankirchner, Alexander Fromm: Solving fully coupled FBSDEs by minimizing a directly calculable error functional Preprint on hal, 2018.
- Alexander Fromm: Theory and applications of decoupling fields for FBSDEs. PhD thesis, 2015.

Thank you!