Reflected BSDEs in non-convex domains

Adrien Richou (Université de Bordeaux)
joint work with

J.-F. Chassagneux (Université Paris Cité) and S. Nadtochiy (Illinois
Institute of Technology)

9th colloquium on BSDEs and Mean Field Systems 27th June 2022



why defining a notion of conditional expectation constrainted in a non-convex domain?



Figure: https://www.touteleurope.eu

A known solution

We can define a distance function d in the domain \mathcal{D} and then consider a Fréchet mean for a r.v. X with values in \mathcal{D} :

$$\tilde{\mathbb{E}}[X] \in \arg\min_{y \in \mathcal{D}} \mathbb{E}[d^2(y, X)].$$

Rem: If \mathcal{D} is convex, nothing new here...







We can define a conditional version of the Frechet-mean.

$$\tilde{\mathbb{E}}[X|\mathcal{F}] \in \arg\min_{y \in \mathcal{D}} \mathbb{E}[d^2(y,X)|\mathcal{F}].$$

Problem: the tower property does not hold!

$$\tilde{\mathbb{E}}[X] \neq \tilde{\mathbb{E}}[\tilde{\mathbb{E}}[X|\mathcal{F}]].$$

We can define a conditional version of the Frechet-mean.

$$\tilde{\mathbb{E}}[X|\mathcal{F}] \in \underset{y \in \mathcal{D}}{\arg\min} \, \mathbb{E}[d^2(y,X)|\mathcal{F}].$$

Problem: the tower property does not hold!

$$\tilde{\mathbb{E}}[X] \neq \tilde{\mathbb{E}}[\tilde{\mathbb{E}}[X|\mathcal{F}]].$$

Solution: A reflected BSDE (with null generator) satisfies the tower property by definition.

Reflected BSDEs

We consider W a d-dimensional Brownian motion, $(\mathcal{F}_t)_{t\geqslant 0}$ its natural filtration (augmented), T>0, $\xi\in L^2(\mathcal{F}_T)$.

Let \mathcal{D} a domain (open connected subset of \mathbb{R}^d). We are looking for a triplet $(Y, Z, K) \in \mathcal{S}^2 \times \mathcal{H}^2 \times \mathcal{K}^1$ i.e.

$$\mathbb{E}\left[\sup_{t\in[0,T]}|Y_t|^2+\int_0^T|Z_t|^2dt+\int_0^Td\mathsf{Var}_t(K)\right]<+\infty,$$

that satisfies

$$\begin{cases} (i) \ Y_t = \xi + \int_t^T f(s, Y_s, Z_s) \mathrm{d}s - \int_t^T \mathrm{d}K_s - \int_t^T Z_s \mathrm{d}W_s, & 0 \leqslant t \leqslant T, \\ (ii) \ Y_t \in \bar{\mathcal{D}} \ \text{a.s.}, & K_t = \int_0^t \mathfrak{n}(Y_s) \mathrm{d}\mathrm{Var}_s(K), & 0 \leqslant t \leqslant T, \end{cases}$$

$$(1)$$

where $\mathfrak n$ is the unit outward normal to $\partial \mathcal D$, extended as zero into $\mathcal D$.



Some references

- Convex domain: [Gégout-Petit Pardoux '96]
- Extensions to random domains [Klimsiak Rozkosz Słomiński '15], jumps [Fakhouri Ouknine Ren '18], oblique reflection [Chassagneux Richou '20]
- Dimension 1: [El Karoui Kapoudjian Pardoux Peng Quenez '97]
 [Cvitanic Karatzas '96] [Dumitrescu Quenez Sulem '16] [Grigorova Imkeller Offen Ouknine Quenez '17]...

Applications:

- ▶ EDP [Klimsiak Rozkosz Słomiński '18]
- American options
- Optimal switching problems [Hamadène Zhang '10] [Hu Tang '10]

All these results concern convex domains. Non-convex domains:

- [Gayduk Nadtochiy '20] Market microstructure model with a Control-stopping game
- [Briand Hibon '21] Particule system approximation for mean reflected BSDEs.

Results of Gégout-Petit and Pardoux

Assumptions:

- $ightharpoonup \mathcal{D}$ convex, $\xi \in \mathcal{D}$,
- f Lipschitz with respect to y and z,
- $\mathbb{E}[|\xi|^2 + \int_0^T |f(.,0,0)|^2 dt] < +\infty$

Theorem

There exists a unique solution to the reflected BSDE.



Proof of the uniqueness

We take two solutions (Y, Z, K) and (Y', Z', K'):

$$\begin{split} &|\delta Y_{t}|^{2} + \int_{t}^{T} |\delta Z_{s}|^{2} ds \\ &= \int_{t}^{T} 2(Y_{s} - Y'_{s}).(f(s, Y_{s}, Z_{s}) - f(s, Y'_{s}, Z'_{s})) ds + \int_{t}^{T} dM_{s} \\ &+ 2 \int_{t}^{T} (Y'_{s} - Y_{s}) dK_{s} + 2 \int_{t}^{T} (Y_{s} - Y'_{s}) dK'_{s} \end{split}$$

Proof of the existence

We consider a penalization approximation of the BSDE:

$$Y_t^n = \xi + \int_t^T f(t, Y_t^n, Z_t^n) dt - \int_t^T n\phi(Y_t^n) \nabla \phi(Y_t^n) dt - \int_t^T Z_s^n dW_s$$

with $\phi(y) := d(y, \mathcal{D})$. We have following estimates:

- $\mathbb{E}[\sup_{t\in[0,T]}|Y_t^n|^2] + \mathbb{E}[\int_0^T|Z_t^n|^2dt] \leqslant C$
- $n\mathbb{E}[\sup_{t\in[0,T]}\phi^2(Y^n_t)] + \mathbb{E}[\int_0^T n^2\phi^2(Y^n_t)dt] \leqslant C.$



The non-convex case

Assumptions:

- $\mathcal{D} = \{x \in \mathbb{R}^d | \phi(x) < 0\} \text{ with } \phi : \mathbb{R}^d \to \mathbb{R} \ C^2,$
- ▶ $|\nabla \phi(y)| > 0$ for all $y \in \partial \mathcal{D}$,
- ▶ D bounded,
- ▶ $\xi \in \mathcal{D}$, f(.,0,0) bounded.

To simplify the presentation: f = 0.

Uniqueness

Exterior sphere property

There exists R_0 such that

$$(y - y') \cdot \mathfrak{n}(y) + \frac{1}{2R_0} |y - y'|^2 \geqslant 0 , \quad \forall y \in \partial \mathcal{D}, \ y' \in \bar{\mathcal{D}}.$$
 (2)

Uniqueness

Exterior sphere property

There exists R_0 such that

$$(y - y') \cdot \mathfrak{n}(y) + \frac{1}{2R_0} |y - y'|^2 \geqslant 0 , \quad \forall y \in \partial \mathcal{D}, \ y' \in \bar{\mathcal{D}}.$$
 (2)

We take two solutions (Y, Z, K) and (Y', Z', K'):

$$\begin{split} &\Gamma_t |\delta Y_t|^2 + \int_t^T \Gamma_s |\delta Z_s|^2 ds \\ &= \int_t^T dM_s - 2 \int_t^T \Gamma_s \left(2(Y_s - Y_s') dK_s + \frac{1}{R_0} |\delta Y_s|^2 d\mathsf{Var}_s(K) \right) \\ &- 2 \int_t^T \Gamma_s \left(2(Y_s' - Y_s) dK_s' + \frac{1}{R_0} |\delta Y_s|^2 d\mathsf{Var}_s(K') \right) \end{split}$$

with
$$\Gamma_t = e^{\frac{1}{R_0}(\mathsf{Var}_t(K) + \mathsf{Var}_t(K'))}$$



Uniqueness

Proposition

There exists at most one solution to the reflected BSDE in the class of solutions such that there exists p>1 for which

$$\mathbb{E}\left[e^{\frac{2p}{R_0}\mathrm{Var}_T(K)}\right]<+\infty.$$

Existence

We consider a penalized approximation of the BSDE:

$$Y_t^n = \xi - \int_t^T n\phi^+(Y_t^n) \nabla \phi(Y_t^n) dt - \int_t^T Z_s^n dW_s$$

and we try to get estimates on (Y^n, Z^n) that do not depend on n.

Existence

We consider a penalized approximation of the BSDE:

$$Y_t^n = \xi - \int_t^T n\phi^+(Y_t^n) \nabla \phi(Y_t^n) dt - \int_t^T Z_s^n dW_s$$

and we try to get estimates on (Y^n, Z^n) that do not depend on n. First estimate: we would like to obtain

$$|Y_t^n|^2 + \mathbb{E}_t\left[\int_t^T |Z_s^n|^2 ds\right] \leqslant C \quad \forall t \in [0, T].$$

Existence

We consider a penalized approximation of the BSDE:

$$Y_t^n = \xi - \int_t^T n\phi^+(Y_t^n)\nabla\phi(Y_t^n)dt - \int_t^T Z_s^n dW_s$$

and we try to get estimates on (Y^n, Z^n) that do not depend on n. First estimate: we would like to obtain

$$|Y_t^n|^2 + \mathbb{E}_t\left[\int_t^T |Z_s^n|^2 ds\right] \leqslant C \quad \forall t \in [0, T].$$

If we apply Itô formula to $|Y_t^n|^2$ then we get a term

$$-\int_t^T n\phi^+(Y_t^n)Y_t^n \cdot \nabla\phi(Y_t^n)dt$$

which has no clear sign without extra assumption.



Weak star-shape property

We assume that there exists a convex domain $\mathcal{C} \subset \mathcal{D}$ such that

$$\gamma := \inf_{y \in \partial \mathcal{D}} \nabla \phi_{\mathcal{C}}(y) \cdot \frac{\nabla \phi(y)}{|\nabla \phi(y)|} > 0.$$
 (3)

with $\phi_{\mathcal{C}} = d(.,\mathcal{C})$.

Weak star-shape property

We assume that there exists a convex domain $\mathcal{C} \subset \mathcal{D}$ such that

$$\gamma := \inf_{y \in \partial \mathcal{D}} \nabla \phi_{\mathcal{C}}(y) \cdot \frac{\nabla \phi(y)}{|\nabla \phi(y)|} > 0.$$
 (3)

with $\phi_{\mathcal{C}} = d(., \mathcal{C})$.

Enough to get

$$\mathbb{E}\left[\sup_{t\in[0,T]}|Y_t^n|^2\right] + \mathbb{E}\left[\int_0^T|Z_t^n|^2dt\right] \leqslant C$$

but we are not able to obtain

$$n \mathbb{E} [\sup_{t \in [0,T]} |\phi^+(Y^n_t)|^2] + \mathbb{E} [\int_0^T n^2 |\phi^+(Y^n_t)|^2 dt] \leqslant C!$$



A new penalized BSDE

We consider a new penalized approximation of the BSDE:

$$Y_t^n = \xi - \int_t^T n\phi^+(Y_t^n)(1 + |Z_t^n|^2)\nabla\phi(Y_t^n)dt - \int_t^T Z_s^n dW_s.$$

Existence and uniqueness of a solution for this penalized BSDE?

A new penalized BSDE

We consider a new penalized approximation of the BSDE:

$$Y_t^n = \xi - \int_t^T n\phi^+(Y_t^n)(1 + |Z_t^n|^2)\nabla\phi(Y_t^n)dt - \int_t^T Z_s^n dW_s.$$

Existence and uniqueness of a solution for this penalized BSDE?

[Xing Žitković '18]

We assume that $\xi = g(W_T)$ with g a α -Hölder function, then there exists a Markovian solution $(Y^n, Z^n) \in \mathscr{S}^2 \times \mathscr{H}^2$.

And we get

$$n\mathbb{E}[\sup_{t\in[0,T]}|\phi^+(Y^n_t)|^2]+\mathbb{E}[\int_0^T n^2|\phi^+(Y^n_t)|^2dt]\leqslant C.$$



How to pass to the limit?

[Xing Žitković '18]

there exists $u_n:[0,T]\times\mathbb{R}^d\to\mathbb{R}^d$ and $0<\alpha'_n\leqslant\alpha$ such that $Y_t^n=u^n(t,W_t)$ with

$$\sup_{(t,x)\neq(t',x')} \frac{|u^{n}(t,x)-u^{n}(t',x')|}{|t-t'|^{\alpha'_{n}/2}+|x-x'|^{\alpha'_{n}}} \leqslant C_{n}.$$

Constants C_n and α'_n depends on n only through ess- $\sup_{\omega \in \Omega, t \in [0,T]} |n\phi^+(Y_t^n)|$.

Proposition

There exists C independent with n such that

$$\operatorname{ess-sup}_{\omega \in \Omega, t \in [0,T]} |n\phi^+(Y_t^n)| < C.$$

Then we can use compacity argument to get $u_n \rightarrow u$.



An existence result in the Markovian framework

Theorem

Assumptions: weak star-shape property + Markovian framework. There exists a unique solution (Y,Z,K) to the reflected BSDE such that, for all $\beta>0$,

$$\mathbb{E}[e^{\beta \mathsf{Var}_{\mathcal{T}}(K)}] < +\infty.$$

Back to the non Markovian framework

Theorem

Let us assume that the weak star-shape property and

$$|\phi_{\mathcal{C}}^{+}(\xi)|_{\mathscr{L}^{\infty}} < \frac{\gamma R_{0}}{2} \text{ and }$$

$$\nabla \phi_{\mathcal{C}}(y) \cdot f(s, y, z) \leqslant 0, \quad \forall s, y, z \in [0, T] \times \bar{\mathcal{D}} \backslash \mathcal{C} \times \mathbb{R}^{d \times d'},$$

• or $\sup_{x \in \mathcal{D}} \phi_{\mathcal{C}}^+(x) < \frac{\gamma R_0}{2}$.

Then there exists a unique solution (Y, Z, K) such that

$$\mathbb{E}\left[e^{\frac{2p}{R_0}\mathrm{Var}_T(K)}\right]<+\infty.$$



Proof

- \triangleright A priori estimate on Var(K) to get the exponential integrability.
- Uniqueness follows.
- Existence result for the smooth discrete path dependent framework, i.e. $\xi = g(W_{t_0}, ..., W_{t_n})$ by iterating the Markovian result.
- For a general ξ , we approximate it by a sequence of discrete path dependent terminal conditions. Need a stability result.

Link with martingales with prescribed terminal condition on manifolds

f = 0

- If ξ is on a "concave" part of the boundary, then Y stays on the boundary: we get a martingale on the boundary manifold. References [Picard '91] [Kendall '90] [Picard '94] [Darling '95]
- ▶ Uniqueness can fall down when d > 2 even with the weak star shape property.
- Good candidate for a notion of martingale in a flat manifold with a boundary. Work in progess with M. Arnaudon, J.-F. Chassagneux and S. Nadtochiy.

Conjecture (Work in progess with M. Arnaudon, J.-F. Chassagneux and S. Nadtochiy)

d=2, $\mathcal D$ smooth domain simply connected. We should have an existence and uniqueness result for the solution of a reflected BSDE in $\mathcal D$.