

ELECTRICITY DEMAND RESPONSE

A mean-field contract theory approach

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1. Motivation & Intuition

Electricity demand response management

Contract theory

Model with one consumer

2. A principal – MF agents problem

The problem of the representative consumer

Main results

The principal's problem

3. Numerical results

4. Conclusion

5. Bibliography

MOTIVATION & INTUITION

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- ▶ **However:** large variance in the consumer's response to these mechanisms.

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3. How to take into account the large number of consumers?

► Goal of our contribution in **Mean-field moral hazard for optimal energy demand response management** (Mathematical Finance, 2021).

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Asymmetries of information:

Moral Hazard: the agent's behaviour is not observable by the principal (second-best case).

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$$X_t = x_0 - \int_0^t \alpha_s \cdot \mathbf{1}_d ds + \int_0^t \sigma(\beta_s) \cdot dW_s, \quad t \in [0, T], \quad (1)$$

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A control process for the agent is a pair $\nu := (\alpha, \beta) \in \mathcal{U}$:

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- (i) identify a class of contracts, offered by the principal, that are **revealing**: the agent's optimal response can be easily calculated;
- (ii) prove that this restriction is **without loss of generality**, using 2BSDE;
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► The optimal form of contracts is as follows:

$$\xi_T = \xi_0 - \int_0^T \mathcal{H}(X_s, \zeta_s) ds + \int_0^T Z_s dX_s + \frac{1}{2} \int_0^T \Gamma_s d\langle X \rangle_s + \frac{1}{2} R_A \int_0^T Z_s^2 d\langle X \rangle_s,$$

for an optimal choice of $\zeta = (Z, \Gamma)$ and ξ_0 .

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- **Contract theory with many agents:** see for example **Élie and Possamaï** [4] (2019), and **Élie, Mastrolia, and Possamaï** [5] (2018) for a continuum of agents.

A PRINCIPAL – MF AGENTS PROBLEM

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- α , effort to reduce the mean of his consumption;
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- W , d-dim. BM, representing the randomness specific to the agent;
- W° , uni-dim. BM, representing the noise common to all agents.

- Optimisation problem of the representative consumer:

$$V_0^A(\xi) := \sup_{\nu=(\alpha,\beta)} \mathbb{E}^{\mathbb{P}} \left[U_A \left(\xi - \int_0^T (c(\nu_t) - f(X_t)) dt \right) \right], \quad (3)$$

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- The principal chooses (Z, Γ) in order to maximise her profit.
- Principal – multi-agents models : the principal can take advantage of the supplementary information available to her (see [4, 5]).

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- $\hat{\alpha}^*$, the optimal effort of others on the drift of their consumption,
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- ξ_0 , constant chosen by the principal in order to satisfy the participation constraint of the agent.

What is hidden behind this contract ?

The contract is in fact indexed on:

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where $\bar{Z}_t^\mu := \widehat{\mathbb{E}}^{\hat{\mu}} [Z_t^\mu (\hat{X}_t)]$.

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- Contracting on $\hat{\mu}$ or W° leads in fact to the same form of contract.

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Principal's problem:

- ▶ this form of contract, where the principal chooses $\zeta := (Z, \Gamma, Z^\mu)$, is **without loss of generality** \Leftrightarrow second-order BSDE of the mean-field type;
- ▶ from the principal's point of view, the contract ξ is a function of X and μ^X , the conditional law of X . \Leftrightarrow Problem of McKean-Vlasov type.

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with respect to the common noise.

Her problem is reduced to a standard control problem:

$$V^P := \sup_{\zeta \in \mathcal{V}} \mathbb{E} \left[U^P \left(-\mathbb{E}^{\mu^L} [L_T] \right) \right], \quad L_T = \xi_T + \int_0^T g(X_s)ds + \frac{h}{2} \int_0^T d\langle X \rangle_s,$$

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▶ Two state variables: the **conditional** law of X (μ^X) and the **conditional** law of L (μ^L) \Rightarrow HJB technics.

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$$\begin{aligned} \xi_t = \xi_0 & - \underbrace{\int_0^t \mathcal{H}(X_s, \mu_s^X, \zeta_s^*, \alpha_s^*) ds}_{\text{Hamiltonian}} + \underbrace{\int_0^t Z_s^* (dX_s - \tilde{\mathbb{E}}^{\mu_s^X} [d\tilde{X}_s])}_{\text{Penalisation w.r.t the others}} \\ & + \underbrace{\frac{1}{2} \int_0^t \Gamma_s^* d\langle X \rangle_s}_{\text{Compensation for volatility control}} \end{aligned}$$

Optimal indexation on the law

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- Let X° be the consumption **without common noise** (corrected for climatic hazards):

$$dX_t^\circ = -\alpha^*(Z_t^*)dt + \sigma^*(\Gamma_t^*) \cdot dW_t.$$

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$$\xi_T = \xi_0 - \int_0^T \mathcal{H}(X_s, \zeta_s^*) ds + \int_0^T Z_s^* dX_s^\circ + \frac{1}{2} \int_0^T (\Gamma_s^* + R_A |Z_s^*|^2) d\langle X^\circ \rangle_s$$

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- Risk-neutral case ($R_P = 0$) \Rightarrow Classic contract for drift and volatility control, indexed on X° , the part of the deviation that is **actually controlled** by the agent.

NUMERICAL RESULTS

If the energy value discrepancy is linear, i.e. $(f - g)(x) = \delta x$, $x \in \mathbb{R}$:

- ▶ the optimal Z^* and Γ^* are deterministic functions of time;
- ▶ the payment $Z^{\mu,*}$ allows the principal to choose the risk she wants to bear:

$$Z_t^{\mu,*} = -Z_t^* + \frac{R_P}{R_A + R_P} \delta(T - t).$$

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We can compare the efforts and the utility of the principal when she offers contracts indexed by $\zeta^0 = (Z, 0, \Gamma)$:

$$\xi_T = \xi_0 - \int_0^T \mathcal{H}(X_s, \zeta_s^0) ds + \int_0^T Z_s dX_s + \frac{1}{2} \int_0^T (\Gamma_s + R_A Z_s^2) d\langle X \rangle_s,$$

GAIN IN UTILITY FOR THE PRINCIPAL

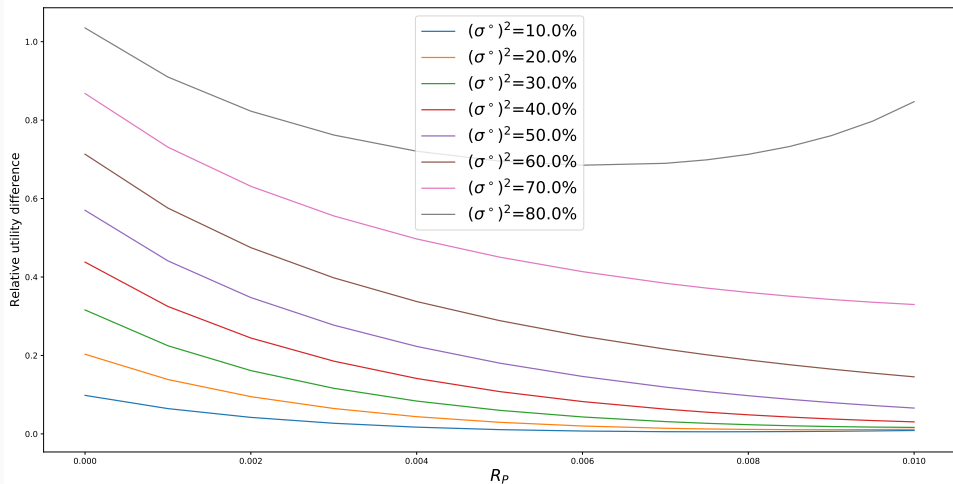


Figure: Relative utility difference.
Variation with respect to R_p and σ^o .

EFFORT OF THE AGENTS

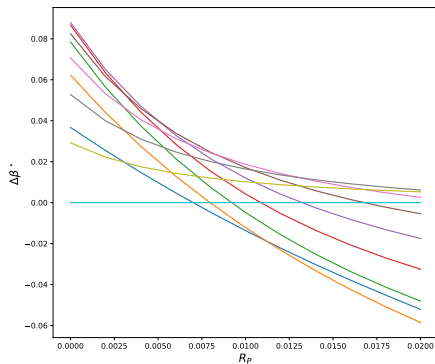
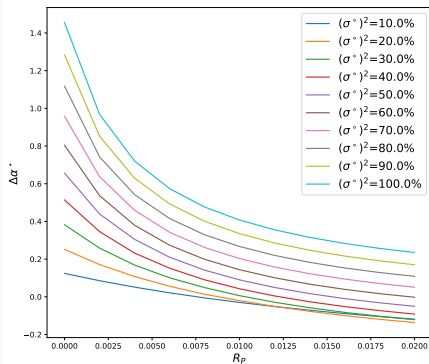


Figure: Relative gain on efforts.
Variation with respect to R_p and σ° .

CONCLUSION

Technical contribution: Extension of PA problems with volatility control to a continuum of agents with mean-field interactions, by developing natural extensions of the 2BSDE theory.

- ▶ While the consumers are in a mean-field game...
- ▶ the principal faces a control problem of McKean Vlasov type.

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Results: At the end, this more sophisticated form of contract:

- ▶ allows the principal to better share the risk induced by the common noise with the agent;
- ▶ provides better incentives to the agents.

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Further works:

- ▶ more general model;
- ▶ application to finance, insurance...

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