## Kolmogorov equations on spaces of measures

 associated to nonlinear filtering processesMattia Martini<br>Università degli Studi di Milano

## Overview

(1) Stochastic filtering

- Nonlinear filtering problem
- Nonlinear filtering equations

2 Kolmogorov equations associated to filtering equations
Itô formula

- Backward equation associated to the Zakai equation
- Backward equation associated to the K.-S. equation


## Kolmogorov equations on spaces of measures

We want to introduce and study a class of backward Kolmogorov equations on

- $\mathcal{M}_{2}^{+}\left(\mathbb{R}^{d}\right), \mathcal{P}_{2}\left(\mathbb{R}^{d}\right)$ : positive and probability measures with finite second moment;
- $\langle\mu, \psi\rangle=\mu(\psi)=\int_{\mathbb{R}^{d}} \psi(x) \mu(\mathrm{d} \boldsymbol{x})$;


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SDEs for measure-valued processes arise naturally in the stochastic filtering framework.

- Many results when there is a density, using stochastic calculus on Hilbert spaces (e.g. Rozovsky [9], Pardoux [8]).
- New tools for calculus on spaces of (probability) measures (e.g. Ambrosio, Gigli \& Savarè [1], P.-L. Lions [5], Carmona \& Delarue [3] ).
- Optimal control with partial observation (e.g. Gozzi \& Święch [4] in the Hilbert setting, or recently Bandini, Cosso, Fuhrman \& Pham [2] on $\mathcal{P}_{2}\left(\mathbb{R}^{d}\right)$ ).


## Stochastic filtering The problem

Signal process

$$
\begin{equation*}
\mathrm{d} X_{t}=b\left(X_{t}\right) \mathrm{d} s+\sigma\left(X_{t}\right) \mathrm{d} W_{t}, \quad X_{0} \in L^{2}\left(\Omega, \mathcal{F}_{0}\right), \quad t \in[0, T] . \tag{1}
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## Observation process

For every $t \in[0, T]$,

$$
\begin{array}{r}
\mathrm{d} Y_{t}=h\left(X_{t}\right) \mathrm{d} t+\mathrm{d} B_{t}, \quad Y_{0}=0, \\
\mathcal{F}_{t}^{Y}=\sigma\left(Y_{s}, 0 \leq s \leq t\right) \vee \mathcal{N}, \tag{2}
\end{array}
$$

where $\mathcal{N}$ are $\mathbb{P}$-negligible sets.

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## Goal

- The signal $X$ is not directly observed;
- The available information is given by $Y$;
- We want to provide an approximation of $X$ given the observation $Y$.


## Stochastic filtering The filter

- Given the information $\mathcal{F}_{t}^{Y}$, the best estimate for $\varphi\left(X_{t}\right)$ is

$$
\mathbb{E}\left[\varphi\left(X_{t}\right) \mid \mathcal{F}_{t}^{\curlyvee}\right] ;
$$

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\mathbb{E}\left[\varphi\left(X_{t}\right) \mid \mathcal{F}_{t}^{Y}\right] ;
$$

- Let $\Pi_{t}$ be the regular conditional probability distribution of $X_{t}$ given $\mathcal{F}_{t}^{Y}$ : for any $A \in \mathcal{B}\left(\mathbb{R}^{d}\right)$

$$
\Pi_{t}(A, \omega)=\mathbb{P}\left(X_{t} \in A \mid \mathcal{F}_{t}^{Y}\right)(\omega), \quad \text { a.e. } \omega
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- For every $\varphi \in \mathrm{C}_{\mathrm{b}}\left(\mathbb{R}^{d}\right)$ and $t \in[0, T]$,

$$
\left\langle\Pi_{t}, \varphi\right\rangle=\mathbb{E}\left[\varphi\left(X_{t}\right) \mid \mathcal{F}_{t}^{Y}\right], \quad \text { a.s. }
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$$
\mathbb{E}\left[\varphi\left(X_{t}\right) \mid \mathcal{F}_{t}^{\gamma}\right] ;
$$

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$$

$\left\{\Pi_{t}=\operatorname{Law}\left(X_{t} \mid \mathcal{F}_{t}^{Y}\right)\right\}_{t \in[0, T]}$ is a $\mathcal{P}\left(\mathbb{R}^{d}\right)$-valued process called filter.

## Stochastic filtering The unnormalized filter

Define $\mathbb{Q}$ by $\left.\frac{\mathrm{d} \mathbb{Q}}{\mathrm{dP}}\right|_{\mathcal{F}_{t}}=M_{t}^{-1}=\exp \left\{-\frac{1}{2} \int_{0}^{t}\left|h\left(X_{s}\right)\right|^{2} \mathrm{~d} s-\int_{0}^{t} h\left(X_{s}\right) \mathrm{d} B_{s}\right\}$.

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## Theorem (Kallianpur-Striebel formula)

The filter $\Pi$ can be represented as

$$
\begin{equation*}
\left\langle\Pi_{t}, \varphi\right\rangle=\frac{\left\langle\rho_{t}, \varphi\right\rangle}{\left\langle\rho_{t}, \mathbf{1}\right\rangle}, \quad t \in[0, T], \varphi \in \mathrm{C}_{\mathrm{b}}\left(\mathbb{R}^{d}\right), \tag{3}
\end{equation*}
$$

where $\left\langle\rho_{t}, \varphi\right\rangle=\mathbb{E}^{\mathbb{Q}}\left[M_{t} \varphi\left(X_{t}\right) \mid \mathcal{F}_{t}^{Y}\right]$.
$\left\{\rho_{t}\right\}_{t \in[0, T]}$ is a $\mathcal{M}^{+}\left(\mathbb{R}^{d}\right)$-valued process called unnormalized filter.

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$\left\{\rho_{t}\right\}_{t \in[0, T]}$ is a $\mathcal{M}^{+}\left(\mathbb{R}^{d}\right)$-valued process called unnormalized filter.
$Y$ is a brownian motion under $\mathbb{Q}$. By Itô formula applied to $M_{t} \varphi(X)$ we obtain

## The Zakai equation (Z)

The unnormalized filter satisfies, for every test $\varphi$,

$$
\begin{equation*}
\mathrm{d}\left\langle\rho_{t}, \varphi\right\rangle=\left\langle\rho_{t}, A \varphi\right\rangle \mathrm{d} t+\left\langle\rho_{t}, h \varphi\right\rangle \mathrm{d} Y_{t}, \quad t \in(0, T], \tag{4}
\end{equation*}
$$

where $A$ is the infinitesimal generator of $X$.

## Stochastic filtering Kushner-Stratonovitch equation

Let $A$ be the generator of $X: A \varphi=b^{\top}\left(D_{x} \varphi\right)+\frac{1}{2} \operatorname{tr}\left\{\left(\mathrm{D}_{x}^{2} \varphi\right) \sigma \sigma^{\top}\right\}$.
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$$

where $Y$ is a Brownian motion under $\mathbb{Q}$.

Using the Kallianpur-Striebel formula

## The Kushner-Stratonovich equation (KS)

The filter satisfies, for every test $\varphi$,

$$
\mathrm{d}\left\langle\Pi_{t}, \varphi\right\rangle=\left\langle\Pi_{t}, A \varphi\right\rangle \mathrm{d} t+\left(\left\langle\Pi_{t}, h \varphi\right\rangle-\left\langle\Pi_{t}, \varphi\right\rangle\left\langle\Pi_{t}, h\right\rangle\right) \mathrm{d} / t, \quad t \in(0, T],
$$

where $\left\{I_{t}\right\}_{t \in[0, T]}$ is called innovation process and is a Brownian motion under $\mathbb{P}$.

## Stochastic filtering Example: Kalman-Bucy filter

Signal:

$$
\begin{array}{r}
\mathrm{d} X_{t}=b_{t} X_{t} \mathrm{~d} t+\sigma_{t} \mathrm{~d} W_{t}, \quad a_{t}^{i j}=\sigma_{t} \sigma_{t}^{\top}, \\
A_{t} \varphi(x)=\mathrm{D}_{x} \varphi(x)^{\top} b_{t} x+\frac{1}{2} \sum_{i, j} a_{t}^{i j} \partial_{i j}^{2} \varphi(x) .
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A_{t} \varphi(x) & =\mathrm{D}_{x} \varphi(x)^{\top} b_{t} X+\frac{1}{2} \sum_{i, j} a_{\mathrm{t}}^{i j} \partial_{i j}^{2} \varphi(x) .
\end{aligned}
$$

Observation:

$$
\mathrm{d} Y_{t}=h_{\mathrm{t}} X_{\mathrm{t}} \mathrm{~d} t+\mathrm{d} B_{\mathrm{t}}, \quad Y_{0}=0 .
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$(X, Y)$ is a gaussian process.

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\mathrm{d}\left\langle\Pi_{\mathrm{t}}, \varphi\right\rangle=\left\langle\Pi_{\mathrm{t}}, A_{s} \varphi\right\rangle \mathrm{d} t+\left\langle\Pi_{\mathrm{t}}, \varphi h_{\mathrm{t}}^{\top} \iota\right\rangle \mathrm{d} l_{\mathrm{t}}-\left\langle\Pi_{\mathrm{t}}, \varphi\right\rangle\left\langle\Pi_{\mathrm{t}}, h^{\top} \iota\right\rangle \mathrm{d} l_{\mathrm{t}},
$$

$\iota(x)=x$.

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$(X, Y)$ is a gaussian process.
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$$

$\iota(x)=x$. Moreover, for $\omega \in \Omega$ fixed, $\Pi_{t}(\omega)$ is gaussian with

- Mean $\hat{X}_{t}$ that solves the SDE

$$
\mathrm{d} \hat{X}_{t}=b_{\mathrm{t}} \hat{X}_{t} \mathrm{~d} t+\gamma_{t} h_{t} \mathrm{~d} l_{t}, \quad I_{t}=Y_{t}-\int_{0}^{t} h_{s} \hat{X}_{s} \mathrm{ds} .
$$

- Deterministic variance that solves the Riccati equation

$$
\frac{\mathrm{d}}{\mathrm{~d} t} \gamma_{t}=\gamma_{t} \boldsymbol{b}_{t}^{\top}+b_{\mathrm{t}} \gamma_{t}+\mathrm{a}_{\mathrm{t}}-\gamma_{\mathrm{t}}\left(h^{\top} h\right) \gamma_{t}^{\top} .
$$

## Itô formula for the Zakai equation

Let $\left\{\rho_{t}\right\}_{t \in[0, T]}$ be a solution to $(\mathrm{Z})$, i.e. for every test $\varphi$

$$
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## Hypotheses (H)

a. $b, \sigma, h$ are Borel-measurable and bounded, $b, \sigma$ are Lipschitz;
b. The matrix $\sigma \sigma^{\top}(x)$ is positive definite for every $x \in \mathbb{R}^{d}$.

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## Proposition (M. [6])

Let $u$ be in $\mathrm{C}_{\mathrm{L}}^{2}\left(\mathcal{M}_{2}^{+}\left(\mathbb{R}^{d}\right)\right)$ and let us assume $(\mathrm{H})$. Then, for every $t \in[0, T]$ :

$$
\mathrm{d} u\left(\rho_{t}\right)=\left\langle\rho_{t}, A \delta_{\mu} u\left(\rho_{t}\right)\right\rangle \mathrm{d} t+\left\langle\rho_{t}, h \delta_{\mu} u\left(\rho_{t}\right)\right\rangle \mathrm{d} Y_{t}+\frac{1}{2}\left\langle\rho_{t} \otimes \rho_{t}, h^{\top} h \delta_{\mu}^{2} u\left(\rho_{t}\right)\right\rangle \mathrm{d} t
$$

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$$

- $\delta_{\mu} u$ is a notions of derivatives for $u: \mathcal{M}^{+}\left(\mathbb{R}^{d}\right) \rightarrow \mathbb{R}$ :

$$
\delta_{\mu} u: \mathcal{M}^{+}\left(\mathbb{R}^{d}\right) \times \mathbb{R}^{d} \rightarrow \mathbb{R}, \quad \delta_{\mu}^{2} u: \mathcal{M}^{+}\left(\mathbb{R}^{d}\right) \times \mathbb{R}^{d} \times \mathbb{R}^{d} \rightarrow \mathbb{R} ;
$$

- Proof by cylindrical approximation: $u(\mu):=g\left(\left\langle\mu, \psi_{1}\right\rangle, \ldots,\left\langle\mu, \psi_{n}\right\rangle\right)$.

The generator $\mathcal{L}: \mathrm{C}_{\mathrm{L}}^{2}\left(\mathcal{M}_{2}^{+}\left(\mathbb{R}^{d}\right)\right) \rightarrow \mathrm{C}_{\mathrm{b}}\left(\mathcal{M}_{2}^{+}\left(\mathbb{R}^{d}\right)\right)$

## The infinitesimal generator of the Zakai equation

The generator $\mathcal{L}: \mathrm{C}_{\mathrm{L}}^{2}\left(\mathcal{M}_{2}^{+}\left(\mathbb{R}^{d}\right)\right) \rightarrow \mathrm{C}_{\mathrm{b}}\left(\mathcal{M}_{2}^{+}\left(\mathbb{R}^{d}\right)\right)$

$$
\begin{aligned}
& (\mathcal{L} u)(\mu)=\left\langle\mu, A \delta_{\mu} u(\mu)\right\rangle+\frac{1}{2}\left\langle\mu \otimes \mu, h^{\top} h \delta_{\mu}^{2} u(\mu)\right\rangle \\
& \quad=\int_{\mathbb{R}^{d}}\left(A \delta_{\mu} u\right)(\mu, x) \mu(\mathrm{d} x)+\frac{1}{2} \int_{\mathbb{R}^{d}} \int_{\mathbb{R}^{d}} h(x)^{\top} h(y) \delta_{\mu}^{2} u(\mu, x, y) \mu(\mathrm{d} x) \mu(\mathrm{d} y) .
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\end{aligned}
$$

## Remark

- Formally $\mathrm{d} \rho_{t}=A^{*} \rho_{t} \mathrm{~d} t+h^{\top} \rho_{t} \mathrm{~d} Y_{t}$, so:

$$
\mathrm{d} u\left(\rho_{t}\right)=\left\langle\boldsymbol{A}^{*} \rho_{t}, \delta_{\mu} u\left(\rho_{t}\right)\right\rangle \mathrm{d} t+\left\langle h^{\top} \rho_{t}, \delta_{\mu} u\left(\rho_{t}\right)\right\rangle \mathrm{d} Y_{t}+\frac{1}{2}\left\langle h^{\top} \rho_{t} \otimes h \rho_{t}, \delta_{\mu}^{2} u\left(\rho_{t}\right)\right\rangle \mathrm{d} t
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- Formally $\mathrm{d} \rho_{t}=A^{*} \rho_{t} \mathrm{~d} t+h^{\top} \rho_{t} \mathrm{~d} Y_{t}$, so:

$$
\mathrm{d} u\left(\rho_{t}\right)=\left\langle A^{*} \rho_{t}, \delta_{\mu} u\left(\rho_{t}\right)\right\rangle \mathrm{d} t+\left\langle h^{\top} \rho_{t}, \delta_{\mu} u\left(\rho_{t}\right)\right\rangle \mathrm{d} Y_{t}+\frac{1}{2}\left\langle h^{\top} \rho_{t} \otimes h \rho_{t}, \delta_{\mu}^{2} u\left(\rho_{t}\right)\right\rangle \mathrm{d} t .
$$

- On $\mathbb{R}$, if $\mathrm{d} X_{t}=b X_{t} \mathrm{~d} t+\sigma X_{t} \mathrm{~d} B_{t}$, then

$$
\mathrm{d} u\left(X_{t}\right)=b X_{t} \mathrm{D}_{x} u\left(X_{t}\right) \mathrm{d} t+\sigma X_{t} \mathrm{D}_{x} u\left(X_{t}\right) \mathrm{d} B_{t}+\frac{1}{2} \sigma^{2} X_{t}^{2} \mathrm{D}_{x}^{2} u\left(X_{t}\right) \mathrm{d} t .
$$

## The backward Kolmogorov equation Existence and uniqueness

Let

$$
\begin{equation*}
(\mathcal{L} u)(\mu)=\left\langle\mu, A \delta_{\mu} u(\mu)\right\rangle+\frac{1}{2}\left\langle\mu \otimes \mu, h^{\top} h \delta_{\mu}^{2} u(\mu)\right\rangle \tag{5}
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Given $\Phi: \mathcal{M}_{2}^{+}\left(\mathbb{R}^{d}\right) \rightarrow \mathbb{R}$, the Backward Kolmogorov equation (BEZ) reads as

$$
\begin{cases}\partial_{s} u(\mu, s)+\mathcal{L} u(\mu, s)=0, & (\mu, s) \in \mathcal{M}_{2}^{+}\left(\mathbb{R}^{d}\right) \times[0, T], \\ u(\mu, T)=\Phi(\mu), & \mu \in \mathcal{M}_{2}^{+}\left(\mathbb{R}^{d}\right) .\end{cases}
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## Theorem (M. [6])

Let $\Phi \in \mathrm{C}_{\mathrm{L}}^{2}\left(\mathcal{M}_{2}^{+}\left(\mathbb{R}^{d}\right)\right)$. Let $(H)$ holds and let us set

$$
\begin{equation*}
u(\mu, s):=\mathbb{E}\left[\Phi\left(\rho_{T}^{s, \mu}\right)\right], \quad(\mu, s) \in \mathcal{M}_{2}^{+}\left(\mathbb{R}^{d}\right) \times[0, T] \tag{6}
\end{equation*}
$$

Then $u$ is the unique classical solution to (BEZ).

## Proof (key steps)

Uniqueness:

- By the Itô formula, every classical solution to (BEZ) has the form

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- since $\Phi \in \mathrm{C}_{\mathrm{L}}^{2}\left(\mathcal{M}_{2}^{+}\left(\mathbb{R}^{d}\right)\right)$ and by the previous point, we conclude by a chain rule.
- By Itô formula and Markov property

$$
\begin{aligned}
\lim _{h \rightarrow 0} \frac{1}{h}[u(\mu, s+h) & -u(\mu, s)] \\
& =-\lim _{h \rightarrow 0} \frac{1}{h} \mathbb{E}\left[\int_{s}^{s+h} \mathcal{L} u\left(\rho_{\tau}^{s, \mu}, s+h\right) \mathrm{d} \tau\right]=-\mathcal{L} u(\mu, s)
\end{aligned}
$$

## The Kushner-Stratonovich equation case

The operator $\mathcal{L}^{K S}: \mathrm{C}_{\mathrm{L}}^{2}\left(\mathcal{P}_{2}\left(\mathbb{R}^{d}\right)\right) \rightarrow \mathrm{C}_{\mathrm{b}}\left(\mathcal{P}_{2}\left(\mathbb{R}^{d}\right)\right)$

$$
\mathcal{L}^{K S} u(\pi)=\left\langle\pi, A \delta_{\mu} u(\pi)\right\rangle+\frac{1}{2}\left\langle\pi \otimes \pi,(h-\pi(h))^{\top}(h-\pi(h)) \delta_{\mu}^{2} u(\pi)\right\rangle .
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$$

Given $\Phi: \mathcal{P}_{2}\left(\mathbb{R}^{d}\right) \rightarrow \mathbb{R}$, the Backward Kolmogorov equation (BEKS) reads as

$$
\begin{cases}\partial_{s} u(\pi, s)+\mathcal{L}^{K s} u(\pi, s)=0, & (\pi, s) \in \mathcal{P}_{2}\left(\mathbb{R}^{d}\right) \times[0, T], \\ u(\pi, T)=\Phi(\pi), & \pi \in \mathcal{P}_{2}\left(\mathbb{R}^{d}\right) .\end{cases}
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$$

Let $\left\{\Pi_{t}^{s, \pi}\right\}_{t \in[s, T]}$ be a solution to (KS) starting at time $s$ from $\pi \in \mathcal{P}_{2}\left(\mathbb{R}^{d}\right)$ :

$$
\begin{equation*}
\mathrm{d}\left\langle\Pi_{\mathrm{t}}, \psi\right\rangle=\left\langle\Pi_{\mathrm{t}}, A \psi\right\rangle \mathrm{d} t+\left(\left\langle\Pi_{\mathrm{t}}, h \psi\right\rangle-\left\langle\Pi_{\mathrm{t}}, \psi\right\rangle\left\langle\Pi_{\mathrm{t}}, h\right\rangle\right) \cdot \mathrm{d} I_{\mathrm{t}}, \quad t \in(0, T] . \tag{7}
\end{equation*}
$$

## Theorem (M. [6])

Let $\Phi \in \mathrm{C}_{\mathrm{L}}^{2}\left(\mathcal{P}_{2}\left(\mathbb{R}^{d}\right)\right)$. Let $(H)$ holds and let us set

$$
u(\pi, s)=\mathbb{E}\left[\Phi\left(\Pi_{T}^{s, \pi}\right)\right], \quad(\pi, s) \in \mathcal{P}_{2}\left(\mathbb{R}^{d}\right) \times[0, T]
$$

Then $u$ is the unique classical solution to (BEKS).

## The Kushner-Stratonovich equation case Viscosity approach

$K \subset \mathbb{R}^{d}$ compact, $\Phi \in \mathrm{C}_{\mathrm{b}}\left(\mathcal{P}_{2}(K)\right)$ :

$$
\begin{cases}\partial_{s} u(\pi, s)+\mathcal{L}^{K s} u(\pi, s)=0, & (\pi, s) \in \mathcal{P}_{2}(K) \times(0, T], \\ u(\pi, T)=\Phi(\pi), & \pi \in \mathcal{P}_{2}(K) .\end{cases}
$$

Let $\left\{\eta_{t}^{S, \pi}\right\}_{t \in[s, T]}$ be a solution to (KS) confined in $\mathcal{P}_{2}(K)$.

## Theorem (M. [7])

Let $\Phi \in \mathrm{C}_{\mathrm{b}}\left(\mathcal{P}_{2}(K)\right)$. Let $(H)$ holds and let us set

$$
u(\pi, s)=\mathbb{E}\left[\Phi\left(\Pi_{T}^{s, \pi}\right)\right], \quad(\pi, s) \in \mathcal{P}_{2}(K) \times(0, T]
$$

Then $u$ is the unique viscosity solution to (BEKS).

## Proof of the comparison principle (Key steps)

Let $u_{1}$ and $u_{2}$ be respectively a subsolution and a supersolution to (BEKS).
Moreover, let $u(\pi, s):=\mathbb{E}\left[\Phi\left(\Pi_{T}^{s, \pi}\right)\right]$. We want to show that $u_{1} \leq u_{2}$.

- Show: $u_{1} \leq u$ and $u \leq u_{2}$.
- Introduce a family of approximated problems:

$$
\begin{cases}\partial_{s} u(\pi, s)+\mathcal{L}^{K S} u(\pi, s)=0, & (\pi, s) \in \mathcal{P}_{2}(K) \times(0, T] \\ u(\pi, T)=\Phi_{n}(\pi) \in \mathrm{C}_{\mathrm{L}}^{2}\left(\mathcal{P}_{2}(K)\right), & \pi \in \mathcal{P}_{2}(K)\end{cases}
$$

- $u^{n}(\pi, s):=\mathbb{E}\left[\Phi_{n}\left(\Pi_{T}^{s, \pi}\right)\right]$ is a classical solution to the approximated problem which converges to $u$.
- Using the Borwein-Preiss variational principle with a suitable smooth gauge-type function, we introduce a suitable test function that allows us to conclude.


## Thank you!

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## Spaces of measures Linear functional derivatives

## Linear functional derivative

$u: \mathcal{M}^{+}\left(\mathbb{R}^{d}\right) \rightarrow \mathbb{R}$ is in $\mathrm{C}_{\mathrm{b}}^{1}\left(\mathcal{M}^{+}\left(\mathbb{R}^{d}\right)\right)$ if it is continuous, bounded and if exists

$$
\delta_{\mu} u: \mathcal{M}^{+}\left(\mathbb{R}^{d}\right) \times \mathbb{R}^{d} \ni(\mu, x) \mapsto \delta_{\mu} u(\mu, x) \in \mathbb{R},
$$

bounded, continuous and such that for all $\mu$ and $\mu^{\prime}$ in $\mathcal{M}^{+}\left(\mathbb{R}^{d}\right)$, it holds:

$$
\begin{equation*}
u\left(\mu^{\prime}\right)-u(\mu)=\int_{0}^{1} \int_{\mathbb{R}^{d}} \delta_{\mu} u\left(t \mu^{\prime}+(1-t) \mu, x\right)\left[\mu^{\prime}-\mu\right](\mathrm{d} x) \mathrm{d} t \tag{8}
\end{equation*}
$$

Similarly we can define $\mathrm{C}_{\mathrm{b}}^{k}\left(\mathcal{M}^{+}\left(\mathbb{R}^{d}\right)\right), k \in \mathbb{N}$.

## Example

Let $g \in \mathrm{C}_{\mathrm{b}}^{2}(\mathbb{R})$ and let $\psi \in \mathrm{C}_{\mathrm{b}}\left(\mathbb{R}^{d}\right)$. We define

$$
u: \mathcal{M}^{+}\left(\mathbb{R}^{d}\right) \ni \mu \mapsto g(\langle\mu, \psi\rangle) \in \mathbb{R} .
$$

Then $u \in \mathrm{C}_{\mathrm{b}}^{2}\left(\mathcal{M}^{+}\left(\mathbb{R}^{d}\right)\right)$ and it holds:

$$
\delta_{\mu} u(\mu, x)=g^{\prime}(\langle\mu, \psi\rangle) \psi(x), \quad \delta_{\mu}^{2} u(\mu, x, y)=g^{\prime \prime}(\langle\mu, \psi\rangle) \psi(x) \psi(y)
$$

## Spaces of measures L-derivatives

## The space $\mathrm{C}_{\mathrm{L}}^{2}\left(\mathcal{M}^{+}\left(\mathbb{R}^{d}\right)\right)$

$u: \mathcal{M}^{+}\left(\mathbb{R}^{d}\right) \rightarrow \mathbb{R}$ is in $\mathrm{C}_{\mathrm{L}}^{2}\left(\mathcal{M}^{+}\left(\mathbb{R}^{d}\right)\right)$ if:
a. $u$ is in $\mathrm{C}_{\mathrm{b}}^{2}\left(\mathcal{M}^{+}\left(\mathbb{R}^{d}\right)\right)$;
b. $\mathbb{R}^{d} \ni x \mapsto \delta_{\mu} u(\mu, x) \in \mathbb{R}$ is twice differentiable, with continuous and bounded derivatives on $\mathcal{M}^{+}\left(\mathbb{R}^{d}\right) \times \mathbb{R}^{d}$;
We set

$$
\mathrm{D}_{\mu} u(\mu, x):=\mathrm{D}_{\chi} \delta_{\mu} u(\mu, x) \in \mathbb{R}^{d}
$$

## Remark

On $\mathcal{P}_{2}\left(\mathbb{R}^{d}\right)$, the derivative $\mathrm{D}_{\mu} u$ coincides with the one introduced by P.-L. Lions through the lifting procedure in the context of mean field games ([5, 3]).

## Itô formula Sketch of the proof

1. Prove the formula for functions of the form

$$
u: \mathcal{M}_{2}^{+}\left(\mathbb{R}^{d}\right) \ni \mu \mapsto g\left(\left\langle\mu, \psi_{1}\right\rangle, \ldots,\left\langle\mu, \psi_{n}\right\rangle\right)
$$

exploiting classical Itô formula and the the Zakai equation.
2. Prove the formula for functions of the form

$$
u(\mu)=\left\langle\frac{\mu^{r}}{\mu\left(\mathbb{R}^{d}\right)^{r}}, \varphi\left(\cdot, \ldots, \cdot, \mu\left(\mathbb{R}^{d}\right)\right)\right\rangle
$$

by approximation, where $\varphi: \mathbb{R}^{d \times r+1} \rightarrow \mathbb{R}$ is symmetrical in the first $r$ arguments.
3. Prove the formula for functions in $\mathrm{C}_{\mathrm{L}}^{2}\left(\mathcal{M}_{2}^{+}\left(\mathbb{R}^{d}\right)\right)$ by approximation.

## The backward Kolmogorov equation Existence and uniqueness

## Theorem (M. [6])

Let us set

$$
\begin{equation*}
u(\mu, s)=\mathbb{E}\left[\Phi\left(\rho_{T}^{s, \mu}\right)\right] \tag{9}
\end{equation*}
$$

where $\rho_{T}^{s, \mu}$ is the weak solution to the Zakai equation starting at time sfrom $\mu \in \mathcal{M}_{2}^{+}\left(\mathbb{R}^{d}\right)$, $\Phi \in \mathrm{C}_{\mathrm{L}}^{2}\left(\mathcal{M}_{2}^{+}\left(\mathbb{R}^{d}\right)\right)$ and let $(H)$ hold. Then $u$ is the unique classical solution to the backward Kolmogorov equation (BEZ).

## Proof (uniqueness)

We show that if $u$ is a classical solution to (BEZ), then $u(\mu, s)=\mathbb{E}\left[\Phi\left(\rho_{T}^{s, \mu}\right)\right]$.

- By the Itô formula

$$
u\left(\rho_{T}^{s, \mu}, T\right)-u\left(\rho_{s}^{s, \mu}, s\right)=\int_{s}^{T}\left\{\partial_{s} u\left(\rho_{\tau}^{s, \mu}, \tau\right)+\mathcal{L} u\left(\rho_{\tau}^{s, \mu}, \tau\right)\right\} \mathrm{d} \tau+\int_{s}^{T} \mathcal{G} u\left(\rho_{\tau}^{s, \mu}, \tau\right) \cdot \mathrm{d} Y_{\tau}
$$

- By taking the expectation and since $u$ solves (BEZ)

$$
\mathbb{E}\left[\Phi\left(\rho_{T}^{s, \mu}\right)\right]-u(\mu, s)=\mathbb{E}\left[\int_{s}^{T} \mathcal{G} u\left(\rho_{\tau}^{\mathrm{s}, \mu}, \tau\right) \cdot \mathrm{d} Y_{\tau}\right]
$$

- The rhs is zero since the integral is a martingale, thus $u(\mu, s)=\mathbb{E}\left[\Phi\left(\rho_{T}^{s, \mu}\right)\right]$.


## The backward Kolmogorov equation Existence and uniqueness

## Proof (existence)

Let $u(\mu, s)=\mathbb{E}\left[\Phi\left(\rho_{T}^{s, \mu}\right)\right]$ be our candidate solution.

1. Prove that $\mu \mapsto u(\mu, s)$ is in $\mathrm{C}_{\mathrm{L}}^{2}\left(\mathcal{M}_{2}^{+}\left(\mathbb{R}^{d}\right)\right)$ :

- given a suitable notion of derivative for functions from $\mathrm{C}_{\mathrm{L}}^{2}\left(\mathcal{M}_{2}^{+}\left(\mathbb{R}^{d}\right)\right)$ to $\mathrm{C}_{\mathrm{L}}^{2}\left(\mathcal{M}_{2}^{+}\left(\mathbb{R}^{d}\right)\right.$ ), we show that $\mu \mapsto \rho_{T}^{s, \mu}$ is twice differentiable;
- since $\Phi \in \mathrm{C}_{\mathrm{L}}^{2}\left(\mathcal{M}_{2}^{+}\left(\mathbb{R}^{d}\right)\right)$ and by the previous point, we conclude by a chain rule.

2. Prove the continuity of

$$
[0, T] \ni s \mapsto \mathcal{L} u(\mu, s), \quad[s, T] \times[0, T] \ni(\tau, \sigma) \mapsto \mathcal{L} u\left(\rho_{\tau}^{s, \mu}, \sigma\right) \in L^{2}(\Omega)
$$

3. By the Itô formula and the Markov property

$$
\lim _{h \rightarrow 0} \frac{1}{h}[u(\mu, s+h)-u(\mu, s)]=-\lim _{h \rightarrow 0} \frac{1}{h} \mathbb{E}\left[\int_{s}^{s+h} \mathcal{L} u\left(\rho_{\tau}^{s, \mu}, s+h\right) \mathrm{d} \tau\right]=-\mathcal{L} u(\mu, s)
$$

